



Error Analysis

Error Analysis

PROPAGATION OF ERRORS

IN ADDITION

Let two physical quantities be given as

$$p_1 = P_1 \pm \Delta P_1$$

$$\& p_2 = P_2 \pm \Delta P_2, \text{ then}$$

in the sum $(p_1 + p_2)$, the errors get added

$$\text{i.e. } P_1 + P_2 = P_1 + P_2 \pm (\Delta P_1 + \Delta P_2)$$

★ all operations should be done as per rules of significant fig.

$$\text{Eg: } R_1 = 10.0 \pm 0.1 \Omega$$

$$R_2 = 10.7 \pm 0.1 \Omega$$

$$R_{\text{eff}} = 20.7 \pm 0.2 \Omega$$

IN SUBTRACTION

Let two quantities be given as

$$p_1 = P_1 \pm \Delta P_1$$

$$p_2 = P_2 \pm \Delta P_2, \text{ then}$$

their difference $(p_1 - p_2)$ is given by

$$p_1 - p_2 = P_1 - P_2 \pm (\Delta P_1 + \Delta P_2)$$

IN MULTIPLICATION

Case I: When relative errors are small

Relative error in product is sum of relative errors of terms being multiplied.

$$p_1 = P_1 \pm \Delta P_1 \quad \text{where } \Delta P_1 \ll P_1$$

$$p_2 = P_2 \pm \Delta P_2 \quad \text{where } \Delta P_2 \ll P_2$$

$$q = p_1 p_2$$

$$\ln q = \ln p_1 + \ln p_2$$

$$\frac{dq}{q} = \frac{d\beta_1}{\beta_1} + \frac{d\beta_2}{\beta_2}$$

$$\frac{\Delta q}{q} \approx \frac{\Delta \beta_1}{\beta_1} + \frac{\Delta \beta_2}{\beta_2}$$

$$\beta_1 \beta_2 = q \pm \Delta q$$

Case II: when relative errors are large.

(say >10%) then we need to physically find out the upper and lower bound of the product & report the answer accordingly.

Eg - $V = 10V \pm 10\%$
 $I = 5A \pm 10\%$

$$P_{up} = V_u I_u = (1.1)(5.5) = 60.5W$$

$$P_{Lo} = V_L I_L = (9)(4.5) = 40.5W$$

$$P = 50.5 \pm 10W$$

IN DIVISION

Relative errors get added if relative errors are small.

$$q = \frac{\beta_1}{\beta_2}$$

$$\ln q = \ln \beta_1 - \ln \beta_2$$

$$\frac{dq}{q} = \frac{d\beta_1}{\beta_1} - \frac{d\beta_2}{\beta_2}$$

$$\frac{\Delta q}{q} \approx \frac{\Delta \beta_1}{\beta_1} + \frac{\Delta \beta_2}{\beta_2}$$

However, in case relative errors are large, we will once again need to find upper & lower bounds.

Eg - $V = 10V \pm 10\%$

$$I = 5A \pm 10\%$$

$$R = 2\Omega \pm 20\%$$

$$= 2 \pm 0.4\Omega$$

$$R_u = \frac{11}{4.5}, \quad R_L = \frac{9}{5.5}$$

$$R = \frac{1}{2} \left(\frac{11}{4.5} + \frac{9}{5.5} \right) \pm \frac{1}{2} \left(\frac{11}{4.5} - \frac{9}{5.5} \right)$$

$$= 2.035 \pm 0.405 \Omega$$

IN MULTIPLICATION OF POWERS/SURDS EXPRESSIONS

Here, we estimate the max relative error by taking log & differentiating.

Que.) Find relative error in T in terms of relative error in l and g .

$$T = 2\pi \sqrt{\frac{l}{g}}$$

$$\ln(T) = \frac{1}{2} \ln l - \frac{1}{2} \ln g$$

$$\frac{dT}{T} = \frac{dl}{2l} - \frac{dg}{2g}$$

$$\left| \frac{dT}{T} \right|_{\max} = \frac{1}{2} \left| \frac{dl}{l} \right| + \frac{1}{2} \left| \frac{dg}{g} \right|$$

$$\frac{\Delta T}{T} \approx \frac{1}{2} \frac{\Delta l}{l} + \frac{1}{2} \frac{\Delta g}{g}$$

Que.) $p = \frac{A^a}{B^b}$

$$\frac{\Delta p}{p} \approx a \frac{\Delta A}{A} + b \frac{\Delta B}{B}$$

Que.) Length of pendulum = 1 ± 0.1 m

& $g = 9.8 \pm 0.1 \text{ m/s}^2$

Find T of a pendulum.

$$(T_0 = 2\pi \sqrt{\frac{l}{g}})$$

$$\frac{\Delta T}{T} = \frac{1}{2} \left(\frac{0.1}{1} \right) + \frac{1}{2} \left(\frac{0.1}{9.8} \right)$$

$$\frac{\Delta T}{T} = \frac{1}{2} (0.1) \left[1 + \frac{1}{9.8} \right]$$

$$= \frac{0.1}{2} \left[\frac{9.9}{9.8} \right]$$

$$\frac{\Delta T}{T} \times 100 = \frac{1}{2} (10) + \frac{1}{2} (1) \approx 5.5$$

$$T = 2.077 \pm 5.5\% \rightarrow 0.11039$$

$$T \approx 2.0 \pm 0.1$$

IN ARBITRARY FUNCTIONS

There is no full proof method for finding errors in general functions as some functions are so sensitive that a little change in one quantity can lead to an enormous change in the value of the function.

However, for most well-behaved functions, with reasonably small errors in their parameters, we can find the error in the function as

$$\text{If } W = f(x, y, z)$$

$$\text{then } \Delta W \approx \frac{\partial f}{\partial x} \Delta x + \frac{\partial f}{\partial y} \Delta y + \frac{\partial f}{\partial z} \Delta z$$

$$\text{Eg: } y = \sin(x \pm \Delta x)$$

$$y = \sin x \pm \frac{\partial}{\partial x} \sin(x) \cdot \Delta x$$

$$y = \sin x \pm \cos(x) \cdot \Delta x$$

$$y = f(x \pm \delta x)$$

$$\text{then } y = (\pm \delta x f'(x)) + f(x)$$

$$\text{Eg: } \sin 32^\circ = \underline{0.5299}$$

$$= \frac{1}{2} + \frac{\sqrt{3}}{2} \left(2 \cdot \frac{\pi}{180} \right)_{90}$$

$$= \frac{1}{2} \left(1 + \frac{\sqrt{3}\pi}{90} \right)$$

$$= \underline{0.53023}$$

DIMENSIONS

Fundamental quantities which can be used to express all other physical quantities.

CGS units

Fundamental Dimensions

SI Unit

g.

Mass

Kg.

cm.

length

m.

Sec.

Time

Sec.

K.

$\theta \rightarrow$ Temp.

Kelvin

Cd.

Cd \rightarrow Candela
(luminous Intensity)

Candela

A \rightarrow Current

ampere

n \rightarrow $\frac{\text{moles}}{\text{quantity of matter}}$

- Velocity $L T^{-1}$
- Acceleration $L T^{-2}$
- Force $M L T^{-2}$
- Energy $M L^2 T^{-2}$
- Current A
- Momentum $M L T^{-1}$
- Power $M L^2 T^{-3}$
- Planck's Constant $M L^2 T^{-1}$

$$\left(\frac{E \lambda}{c} = \frac{M L^2 T^{-2} L}{L T^{-1}} \right)$$

Que. Find dimensions:

\rightarrow Electric Potential

$$\rightarrow M L^2 T^{-3} A^{-1}$$

\rightarrow Electric Field

$$\rightarrow M L T^{-3} A^{-1}$$

\rightarrow Resistance

$$\rightarrow M L^2 T^{-3} A^{-2}$$

$\rightarrow \mu_0$

$$\rightarrow \left(\frac{q}{EA} \right) \left(\frac{AT}{M L T^{-3} A^{-1} L^2} \right)$$

$$= M^{-1} L^{-3} A^2 T^4$$

\rightarrow Inductance

$$\rightarrow \left(\frac{\text{Energy}}{i^2} \right) = M L^2 T^{-2} A^{-2}$$

→ Coefficient of viscosity (η) $\left(\frac{F}{\alpha v}\right) \left(\frac{M L T^{-2}}{L L T^{-1}}\right) = M L^{-1} T^{-1}$

Que.) If force (F), velocity (v), acceleration (a) were to be used as fundamental dimensions, what will be dimensions of M, L, T.

$$[M] = F^x v^y a^z$$

$$M = (M L T^{-2})^x (L T^{-1})^y (L T^{-2})^z$$

$$x = 1, \quad x + y + z = 0$$

$$y + z = -1$$

$$-2x - y - 2z = 0$$

$$y + 2z = -2$$

$$z = -1$$

$$y = 0$$

$$M = F^1 a^{-1}$$

$$[L] = x = 0, \quad y + z = 1$$

$$-y - 2z = 0$$

$$y = z, \quad z = -1, \quad y = -2z$$

$$L = v^2 a^{-1}$$

$$[T] = x = 0, \quad y + z = 0$$

$$-y - 2z = 1$$

$$y = 1, \quad z = -1$$

$$T = v a^{-1}$$

Zero Correction = - (Zero error)
 actual value - shown value . shown value - actual value

Que.) T depends on (I, M, g, d)
 I → moment of inertia
 d → distance

$$T = k [I]^x [M]^y [g]^z [d]^w$$

$$T = [M L^2]^x [M]^y [L T^{-2}]^z [L]^w$$

$$x+y=0, \quad 2x+z+w=0$$

$$-2z=1$$

$$z=-\frac{1}{2}$$

$$x=-y, \quad -2y-\frac{1}{2}+w=0$$

$$w-2y=\frac{1}{2}$$

$$x=-\frac{1}{2}(w-\frac{1}{2})$$

$$w=2y+\frac{1}{2}$$

$$y=\frac{5}{2}(w-1)$$

Que.) T depends on (I, Mg, d)

$$T = k [ML^2]^x [M \& T^{-2}]^y [L]^w$$

$$x+y=0$$

$$x=-y$$

$$x=\frac{1}{2}$$

$$2x+y+w=0$$

$$1-\frac{1}{2}+w=0$$

$$w=-\frac{1}{2}$$

$$-2y=1$$

$$y=-\frac{1}{2}$$

$$T = k (I)^{1/2} (Mg)^{-1/2} (d)^{-1/2}$$

$$T = k \sqrt{\frac{I}{Mgd}}$$

